BROADCOM®

Data Sheet

AEAT-9933

10-Bit to 14-Bit Programmable Angular Magnetic Encoder IC for On- and Off-Axis Applications



Description

The Broadcom® AEAT-9933 is an angular magnetic rotary sensor that provides accurate angular measurement over a full 360 degrees of rotation.

It is a sophisticated system that uses integrated Hall sensor elements with complex analog and digital signal processing within a single device.

A simple two-pole magnet rotates to generate the magnetic field, with its poles set perpendicular to the axis of rotation. Wide magnetic field sensor configurations allow on-axis (end-of-shaft) or off-axis (side-of-shaft) modes in application.

The Broadcom AEAT-9933 is a versatile solution capable of supporting a broad range of applications with its robust architecture to measure and deliver both absolute and incremental signals.

The absolute angle measurement provides an instant indication of the magnet's angular position with a selectable and reprogrammable resolution from 10 bits to 14 bits.

When selected, its positioning data is represented in its digital form to be assessed through a standard SSI (parity) and SPI (with CRC and parity option) communication protocol. Where desired, users may also choose to receive its absolute angle position in PWM-encoded output signals (with CRC).

The incremental positions are indicated on ABI and UVW signals with a wide user-configurable resolution from 1 CPR and up to 1024 CPR of ABI signals and pole pairs from 1 to 32 pole pairs (2 to 64 poles) for UVW commutation signals.

Features

- 5V and 3.3V operation
- Programmable 10-bit to 14-bit absolute resolution
- Flexible Incremental ABI resolution ranging from 1 CPR to 1024 CPR
- Commutation angle output UVW 1 to 32 pole-pair
- PWM output with error bit option
- User-programmable zero position, direction, index width, and index position
- Programmable hysteresis
- Absolute output over two-wire SSI, three-wire SSI, and four-wire SPI. Each is available in a different mode.
- Compact QFN-24 leads (4 mm × 4 mm) package
- RoHS compliant
- INL angle correction for high accuracy
- Wide operating temperature: –40°C to 125°C

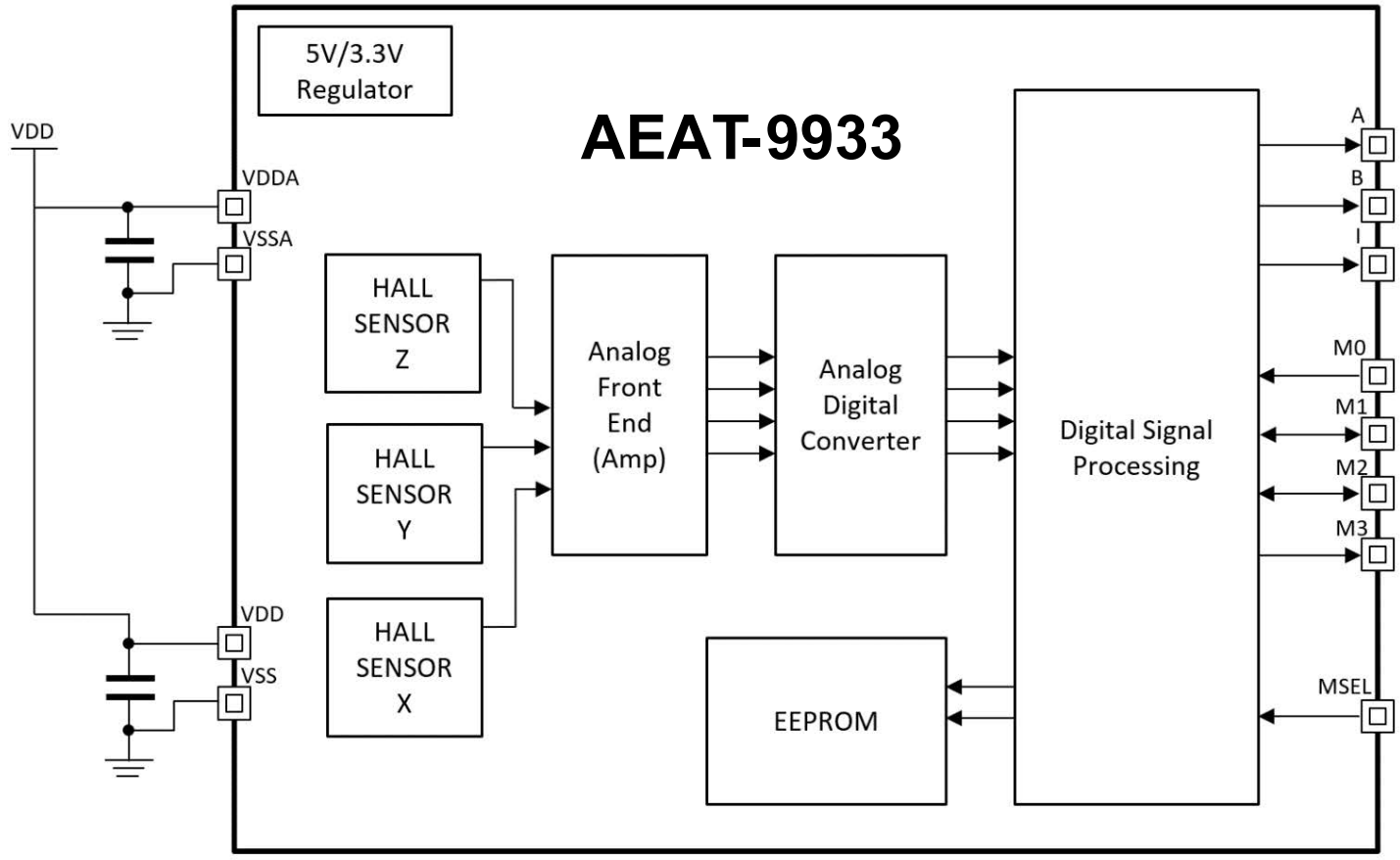
Applications

- Brushless DC motors and stepper motors
- Resolver and potentiometer replacement
- Industrial automation and robotics
- Industrial sewing machines and textiles equipment

NOTE: This product is not specifically designed or manufactured for use in any specific device. Customers are solely responsible for determining the suitability of this product for its intended application and solely liable for all loss, damage, expense, or liability in connection with such use.

Functional Description

Figure 1: AEAT-9933 Block Diagram



The AEAT-9933 is manufactured with a CMOS standard process. It is capable of accurately measuring a magnet's rotational angle when it is placed in alignment and perpendicular to the device by using its integrated Hall sensors to detect its magnetic field. The detected magnetic signals are then taken as input signals to be properly conditioned to negate its nonidealities before inputting them into the analog amplifiers for strength amplification and filtering. After which, the amplified analog signals are fed into the internal analog-to-digital converter (ADC) to be converted into digital signals for the final stage of digital processing. The digital processing provides a digitized output of the absolute and incremental signals.

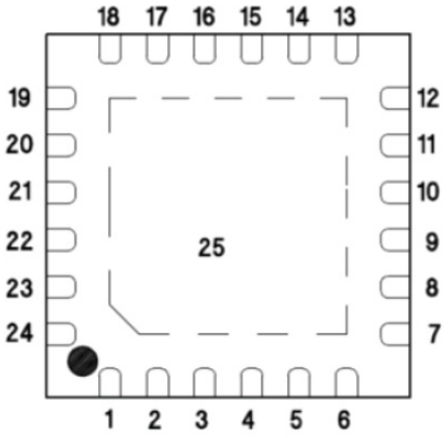
The used magnet should have sufficient magnetic field strength mT to generate the magnetic field for the signal generation, as highlighted in Recommended Magnetic Input Specifications. The device provides digital information of magnetic field strength high MHi and magnetic field strength low MLo from output protocols to indicate whether the magnets are too close or too far away from our device's surface.

Users can access the device's digitized absolute data using standard Synchronous Serial Interface (SSI) or Serial Peripheral Interface (SPI) protocols. In addition, an absolute angular representation can be selected using a pulse width modulated (PWM) signal.

The incremental outputs are available from the digital outputs of their dedicated A, B, and I pins. The U, V, and W commutation outputs are switchable on the general I/O pins.

Pin Assignment

Figure 2: Pin Configurations



Pinout Description

Pin QFN24	Pin Name	I/O	Type	Functional Description
1–6	NC	—	—	No Connection
7	VDDA	—	Power	3.3V/5V Supply Input (Analog)
8	VSSA	—	Power	Supply Ground (Analog)
9	M0	I/O	Digital	SPI3 and SSI Selection/SPI Chip Select/ERR Output
10	M1	I/O	Digital	SPI Data Input/SSI NSL Pin/U Commutation Output (UVW)
11	M2	I/O	Digital	SPI/SSI Clock Input/V Commutation Output (UVW)
12	M3	O	Digital	SPI/SSI Data Out/W Commutation Output (UVW)/PWM Output
13–18	NC	—	—	No Connection
19	MSEL	I	Digital	Mode Selection
20	I	O	Digital	Incremental Index Output (ABI)
21	VDD	—	Power	3.3V/5V Supply Input (Digital)
22	VSS	—	Power	Supply Ground (Digital)
23	B	O	Digital	Incremental B Output (ABI)
24	A	O	Digital	Incremental A Output (ABI)
25	VSS	—	Power	Supply Ground

Electrical Characteristics

Absolute Maximum Ratings

Table 1: Maximum Ratings

Parameter	Symbol	Min.	Max.	Units
Storage Temperature	T_S	–40	125	°C
DC Supply Voltage VDDA Pin	V_{DD}	–0.3	6	V
Input Voltage Range	V_{in}	–0.3	6	V
Electrostatic Discharge (HBM)	—	–4.0	+4.0	kV
Moisture Sensitivity Level	—	—	1	—

CAUTION!

- Subjecting the product to stresses beyond those listed in this section can cause permanent damage to the devices.
- These are stress ratings only and do not imply that the devices will function beyond these ratings. Exposure to the extremes of these conditions for extended periods can affect product reliability.

Recommended Operating Conditions

Table 2: Recommended Operating Conditions for the Encoder IC

Parameter	Symbol	Min.	Typ.	Max.	Units	Notes
Operating Ambient Temperature	T_A	–40	—	125	°C	
DC Supply Voltage to VDD Pin 5V Operation 3.3V Operation	V_{DD}	 4.5 3.0	 5.0 3.3	 5.5 3.6	V	
Incremental Output Frequency	f_{MAX}	—	—	1.0	MHz	Frequency = Velocity (rpm) × CPR / 60
Load Capacitance	C_L	—	—	15	pF	

Systems Parameters

Table 3: Systems Parameters

Parameter	Symbol	Min.	Typ.	Max.	Units	Notes
Current Consumption						
Supply Current Normal Operation Mode	I_{DD}	—	25	—	mA	5V
	I_{DD}	—	24	—	mA	3.3V
Digital Outputs (DO)						
High Level Output Voltage	V_{OH}	VDD – 0.5	—	—	V	Normal operation
Low Level Output Voltage	V_{OL}	—	—	GND + 0.4	V	
Power-Up Time	t_{PwrUp}	—	10	—	ms	
Absolute Output						
Incremental Output						
PWM Output						
Digital Inputs (DI)						
Input High Level	V_{IH}	0.7 × VDD	—	—	V	
Input Low Level	V_{IL}	—	—	0.3 × VDD	V	
Pull-Up Low Level Input Current	I_{IL}	—	—	120	µA	
Pull-Down High Level Input Current	I_{IH}	—	—	120	µA	

NOTE: Electrical characteristics are over the recommended operating conditions. Typical values are specified at VDD = 5.0V and 25°C, at the optimum placement of the magnet.

Encoding Characteristics

Table 4: Encoding Output Characteristics

Parameter	Symbol	Min.	Typ.	Max.	Units	Notes
Absolute Output						
Resolution	RES	10	—	14	Bit	Programmable 10 to 14 bits
Integral Non-Linearity On-Axis	INL_{nom}	—	±0.1	—	Degree	Best fit line, centered magnet. T_A = 25°C, Voltage = 5V, INL Angle correction.
Integral Non-Linearity Off-Axis		—	±0.15	—		
Integral Non-Linearity On-Axis	INL_{dis}	—	±0.2	—	Degree	Best fit line, over displacement of magnet. T_A = 25°C Voltage = 5V.
Integral Non-Linearity Off-Axis		—	±0.3	—		
Integral Non-Linearity On-Axis	INL_{temp}	—	±0.5	—	Degree	Best fit line, over displacement of magnet.T_A = –40°C to +125°C, Voltage = 5V.
Integral Non-Linearity Off-Axis		—	±0.7	—		
Color Monotony		—	1	—	LSB	At stationery, 14-bit absolute.
Output Sampling Rate	f_S	—	10	—	MHz	Based on SSI3 protocol.
Latency		—	80	—	ns	
Incremental Output (Channel ABI)						
Resolution	R_{INC}	1	—	1024	CPR	Programmable
Index Pulse Width	P_O	90	—	360	°e	Programmable options: 90, 180, 270, or 360 °e. See Figure 24.
Index State	—	90	—	360	°e	Programmable options: 90, 180, 270, or 360 °e. See Figure 24.
Relative Angular Accuracy	%	—	10	—	%	Reference to an output period at output A and B, at 512 CPR, 5V. and 3000 rpm.
PWM Output						
PWM Frequency	f_{PWM}	122	—	976	Hz	Adjustable based on PWM settings.
Minimum Pulse Width	P_{WMIN}	—	1	—	µs	
Maximum Pulse Width	P_{WMAX}	—	16384	—	µs	

NOTE: Encoding characteristics are over the recommended operating range unless otherwise specified.

Encoding Timing Characteristics

Table 5: Encoder Timing Characteristics

Parameter	Symbol	Min.	Typ.	Max.	Units	Notes
Incremental Output (ABI and UVW)						
System Reaction Time	t_{delay}	—	10	—	ms	First ABI pulse detection upon power up.

Mechanical and Magnetic Specifications

Recommended Magnetic Input Specifications

Table 6: Magnet Specifications

Parameter	Symbol	Min.	Typ.	Max.	Units	Notes
Diameter						Recommended magnet: Cylindrical magnet or ring magnet diametrically magnetized and one pole pair.
Disc Magnet	d	4	6	—	mm	
Ring Magnet ID		—	15	—	mm	
Ring Magnet OD		—	25	—	mm	
Thickness						
Disc Magnet	t	—	2.5	—	mm	
Ring Magnet		2	6	—	mm	
Magnetic Input Field Magnitude						Required vertical/horizontal component of the magnetic field strength on the die's surface, measured along a concentric circle.
On-Axis (Disc Magnet)	Bpk	45	—	100	mT	
Off-Axis (Ring Magnet)		30	—	150	mT	
Magnet Displacement Radius	R_m	—	—	0.25	mm	Displacement between the magnet axis to the device center.
Recommended Magnet Material and Temperature Drift	—	—	–0.12	—	%/K	NdFeB (Neodymium Iron Boron), grade N35SH.

Figure 3: Direction Definition When the Magnet Rotates

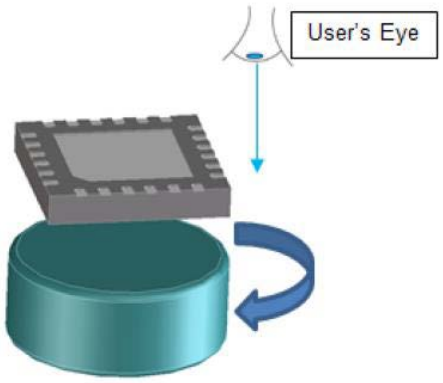
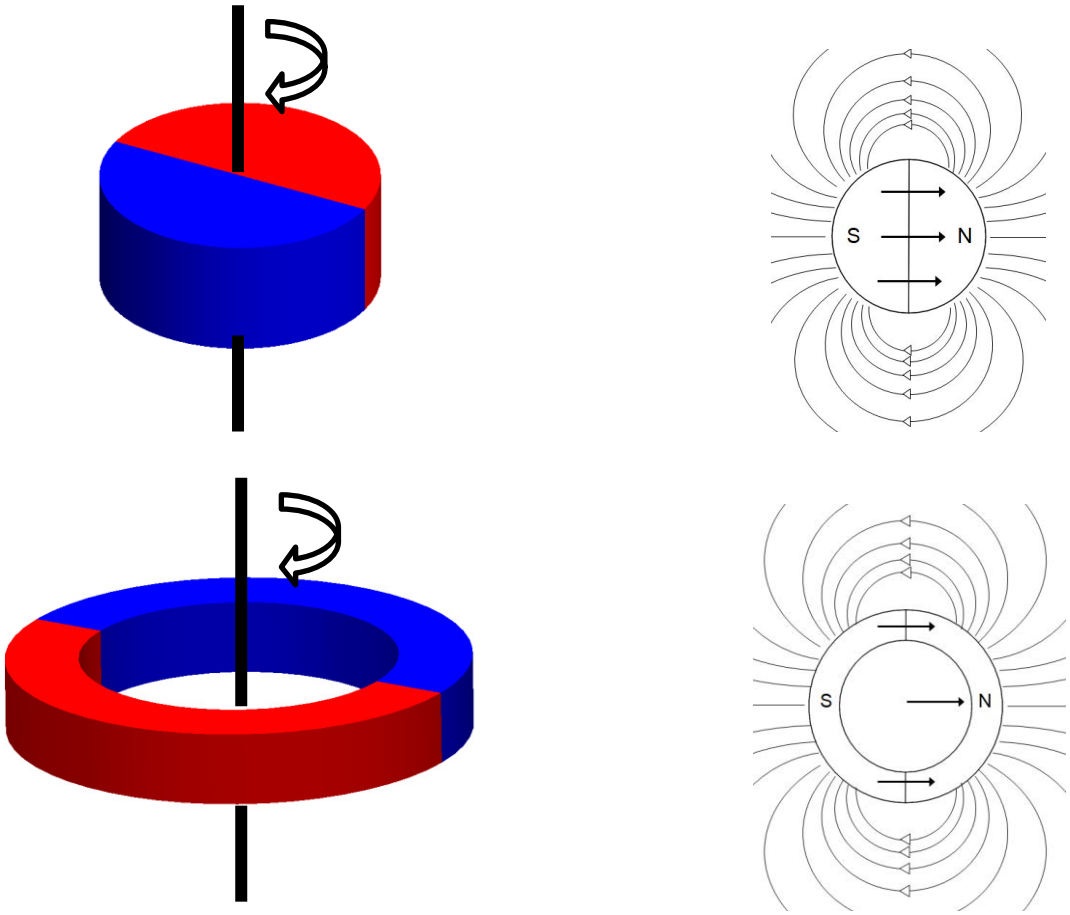


Figure 4: Diametrically Magnetized Magnet



Communication Protocol

The AEAT-9933 has a total of 10 interfaces; one is dedicated for incremental ABI, and the remaining are multiplexed to I/O pins M0, M1, M2, and M3. Each output is configurable using the M0 pin, the MSEL pin, and the PSEL registers, as shown in the following table.

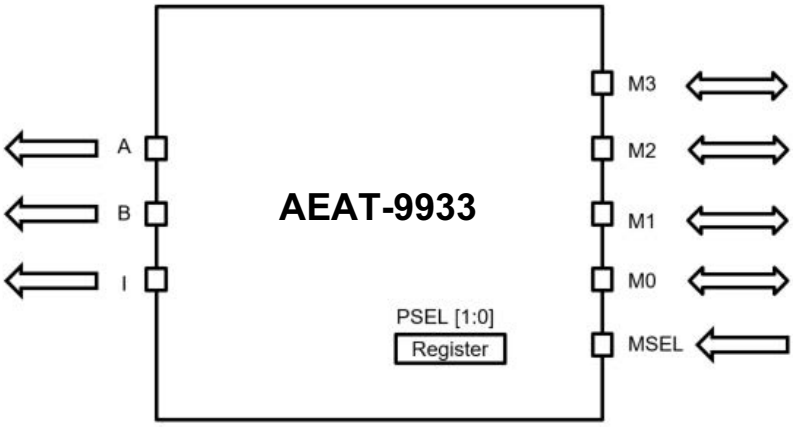
Table 7: Configurable Interface I/O and Selection Table

Pin	Mode									
	SPI-3	**SSI-3(A)**	**SSI-3(B)**	**SSI-2(A)**	**SSI-2(B)**	**SPI-4(A)**	**SPI-4(B)**	**UVW**	**PWM**	**Remarks**
MSEL	0	0	0	0	0	1	1	1	1	I/O Pin
PSEL[1]	x	x	x	x	x	0	0	1	1	Memory
PSEL[0]	x	0	1	0	1	0	1	0	1	Memory
M0	0	1	1	1	1	NCS	NCS	ERR	ERR	I/O Pin
M1	DIN	NSL	NSL	0	0	MOSI	MOSI	U	N/A	I/O Pin
M2	SCK	SCL	SCL	SCL	SCL	SCK	SCK	V	N/A	I/O Pin
M3	DO	DO	DO	DO	DO	MISO	MISO	W	PWM	I/O Pin

NOTE:

- PSEL[1] and PSEL[0] are configurable through the memory.
- MSEL, M0, M1, M2, and M3 are configurable through the I/O pads.

Figure 5: Interface Selection and I/O Pins



SPI4 Protocol

The SPI4 protocol uses four pins from the AEAT-9933. These four pins are shared between UVW, SSI, and SPI protocols. MSEL (input pin) selects either protocol at a time. Assert 1 on the MSEL pin to select the SPI4 protocol.

SPI4 protocols allow users to access memory read or write and position data. They use CPOL=0, CPHA=1 for triggering.

- M0 → SPI_Chip Select (NCS) signal for the SPI protocol, input to the AEAT-9933
- M1 → SPI_Data Input (MOSI) signal for the SPI protocol, input to the AEAT-9933
- M2 → SPI_Clock Input (SCK) signal for the SPI protocol, input to the AEAT-9933
- M3 → SPI_Data Output (MISO) signal for the SPI protocol, output from the AEAT-9933

Figure 6: SPI4 Timing Diagram

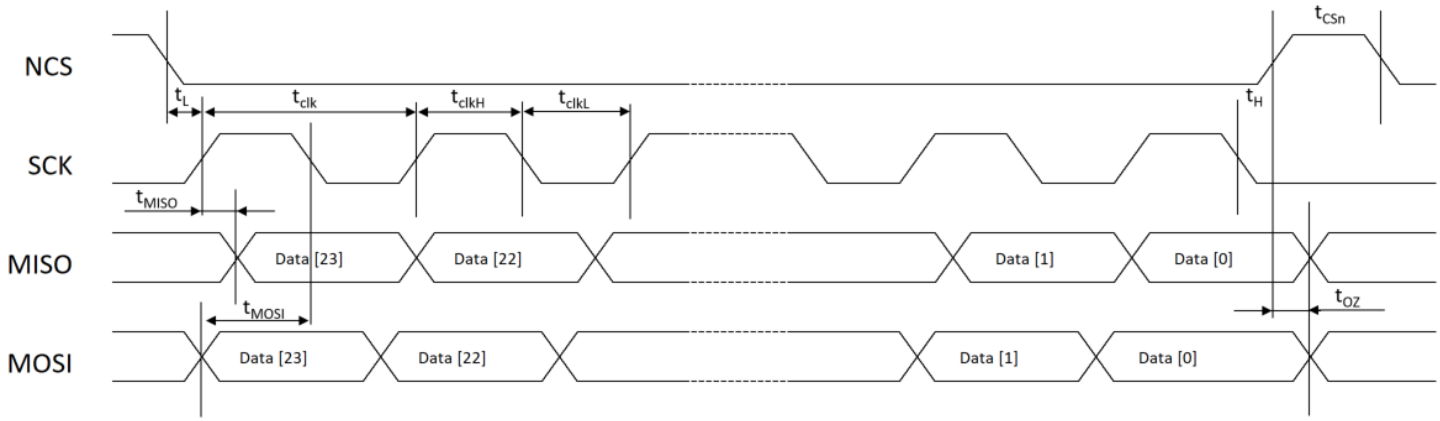


Table 8: SPI4 Timing Characteristics

Symbol	Description	Min.	Typ.	Max.	Units
t_L	Time between the NCS falling edge and the CLK rising edge	350	—	—	ns
t_{clk}	Serial clock period	100	—	—	ns
t_{clkL}	Low period of the serial clock	50	—	—	ns
t_{clkH}	High period of the serial clock	50	—	—	ns
t_H	Time between the last falling edge of the SCK and the rising edge of the NCS	t_{clk} / 2	—	—	ns
t_{CSn}	High time of the NCS between two transmissions	350	—	—	ns
t_{MOSI}	Data input valid to the clock edge	20	—	—	ns
t_{MISO}	SCK edge to data output valid	—	51	—	ns
t_{OZ}	Time between the NCS rising edge and MISO	—	10	—	ns

NOTE: Read back the data to confirm that it is written successfully.

SPI4 Command and Data Frame

Figure 7: SPI4 Read Sequence

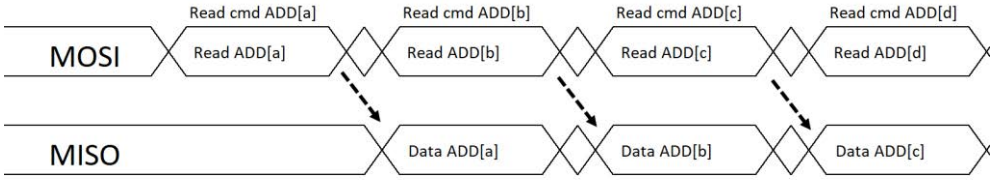


Figure 8: SPI4 Write Sequence

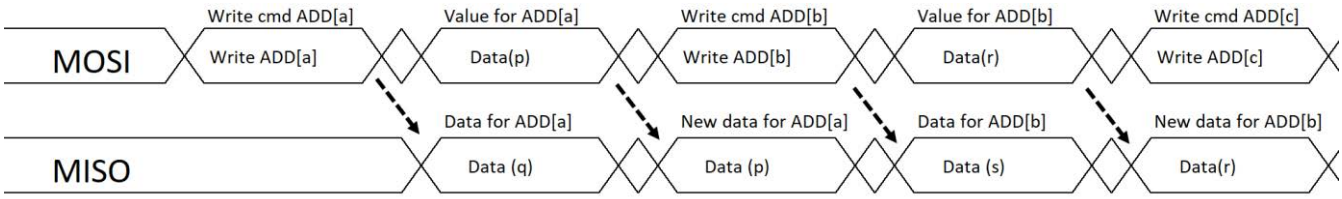


Figure 9: SPI-4(A) 16-Bit (Parity)

	Data Format															
	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
Controller to Peripheral	P	RW	0	0	0	0	0	0	Addr/Data[7:0]							
Peripheral to Controller (memory)	P	EF	0	0	0	0	0	0	Data[7:0]							
Peripheral to Controller (pos 10b)	P	EF	Pos[9:0]										0	0	0	0
Peripheral to Controller (pos 11b)	P	EF	Pos[10:0]											0	0	0
Peripheral to Controller (pos 12b)	P	EF	Pos[11:0]												0	0
Peripheral to Controller (pos 13b)	P	EF	Pos[12:0]													0
Peripheral to Controller (pos 14b)	P	EF	Pos[13:0]													

By default, the chip is configured to SPI4 16-bit selection, PSEL [1] = 0, PSEL [0] = 0 in the register setting.

NOTE: P: Parity; EF: Error Flag; RW: Read = 1, Write = 0.

Figure 10: SPI4-(B) 24-Bit (CRC)

	Data Format																								
	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
Controller to Peripheral	0	RW	0	0	0	0	0	0	Addr/Data[7:0]								CRC[7:0]							
Peripheral to Controller (memory)	W	E	0	0	0	0	0	0	Data[7:0]								CRC[7:0]							
Peripheral to Controller (pos 10b)	W	E	Pos[9:0]										0	0	0	0	CRC[7:0]							
Peripheral to Controller (pos 11b)	W	E	Pos[10:0]											0	0	0	CRC[7:0]							
Peripheral to Controller (pos 12b)	W	E	Pos[11:0]												0	0	CRC[7:0]							
Peripheral to Controller (pos 13b)	W	E	Pos[12:0]													0	CRC[7:0]							
Peripheral to Controller (pos 14b)	W	E	Pos[13:0]														CRC[7:0]							

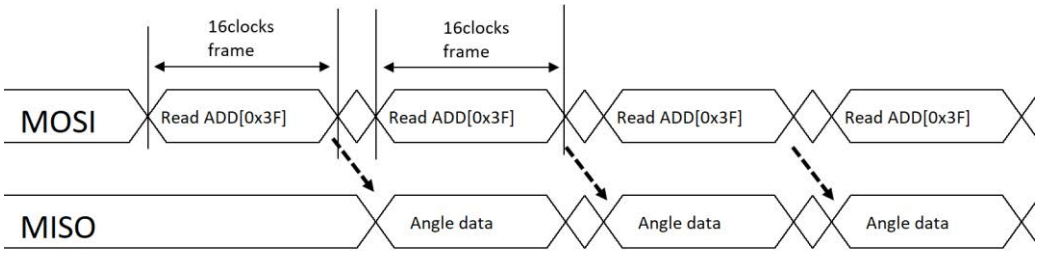
To configure the chip to SPI4 24-bit selection, set PSEL [1] = 0, PSEL [0] = 1 in the register setting.

NOTE: W: Warning; E: Error; RW: Read = 1, Write = 0.

Position Read

Absolute position data can be obtained by sending a read command to address 0x3F.

Figure 11: Read Command



Warning and Error Bit

The error bit is triggered if it is a Magnet High (MHI), Magnet Low (MLO), Memory Error (MEM_Err), or communication error. Details of error bits are available in the register address in the following table.

Table 9: Error Bits Register

Address	Bit								
[Decimal]	[Hex]	7	6	5	4	3	2	1	0
33	0x21	RDY	MHI	MLO	MEM_Err				

- **Magnet High (MHI) Error** – This indicates that the magnet strength detected by the chip is too strong. When this is consistently flagged high, change to a weaker magnet or increase the distance between the chip and the magnet. The value for this alarm is represented as 1.
- **Magnet Low (MLO) Error** – This indicates that the magnet strength detected by the chip is too weak. When this is consistently flagged high, change to a stronger magnet or decrease the distance between the chip and the magnet. The value for this alarm is represented as 1.
- **Ready (RDY)** – The chip is ready, and the ready value is 1.
- **Memory Error (MEM_Err)** – The chip memory content is corrupted (per the CRC check).

SPI3 Protocol

SPI3 protocols allow access only to memory read write. Assert 0 on the MSEL and M0 pins to configure it.

- M1 → SPI_Data Input (DIN) signal for the SPI protocol, input to the AEAT-9933
- M2 → SPI_Clock Input (SCK) signal for the SPI protocol, input to the AEAT-9933
- M3 → SPI_Data Output (DO) signal for the SPI protocol, output from the AEAT-9933

Figure 12: SPI3 Timing Diagram

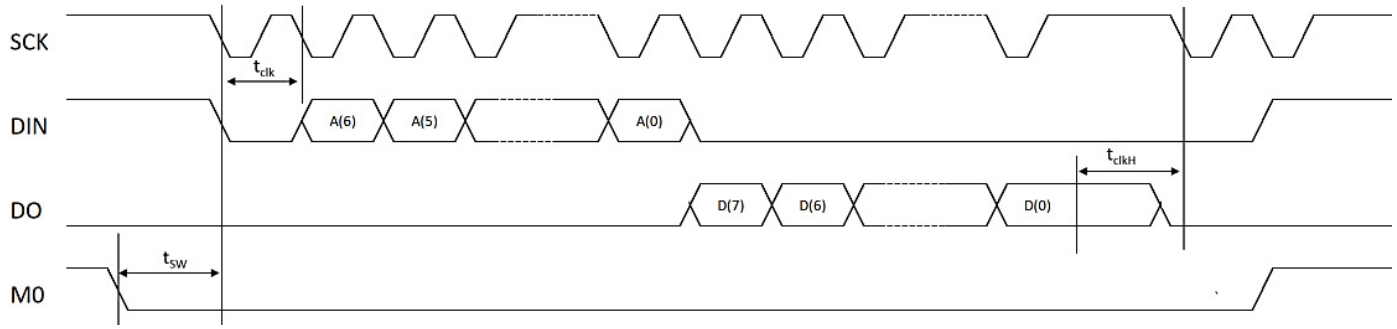


Table 10: SPI3 Timing Characteristics

Symbol	Description	Min.	Typ.	Max.	Units
t_{SW}	Time between the M0 falling edge and the SCK falling edge	1	—	—	µs
t_{clk}	Serial clock period	100	—	—	ns
t_{clkH}	SCK clock high time after the end of the last clock period	300	—	—	ns

NOTE: Read back the data to confirm that it is written successfully.

Figure 13: SPI3 Read

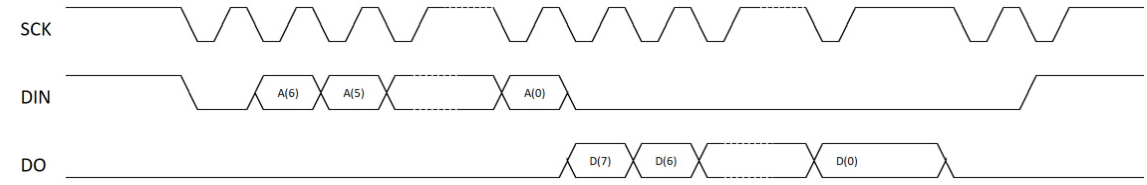
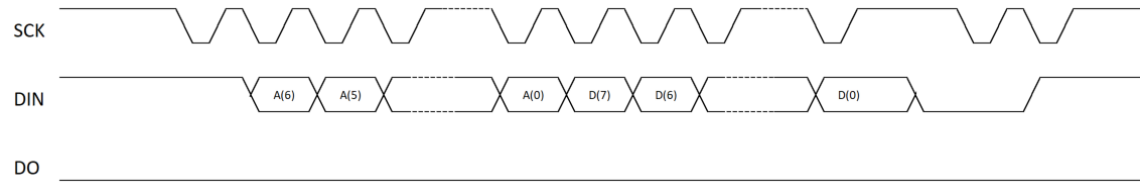


Figure 14: SPI3 Write

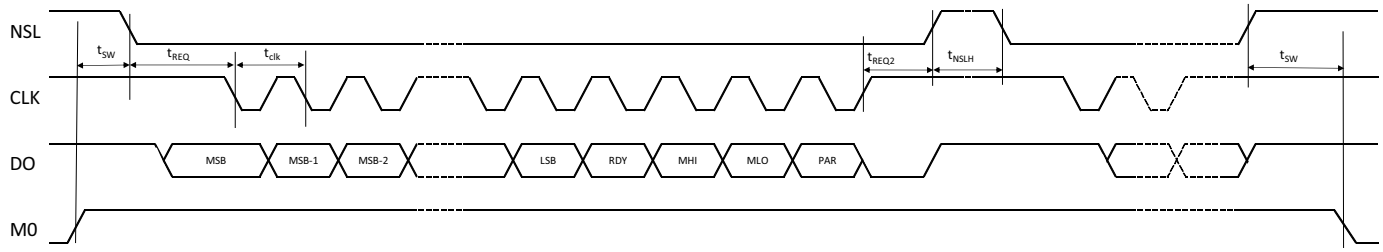


Serial Synchronous Interface Three-Wire

The Serial Synchronous Interface Three-Wire (SSI3) protocol uses three pins from the AEAT-9933. These three pins are shared between the UVW, SSI, and SPI protocols. MSEL (input pin) selects one protocol at a time. Assert 0 on the MSEL pin and 1 on the M0 pin to select the SSI protocol.

- M1 → SSI_NSL Input (NSL) signal for the SSI protocol, input to from the AEAT-9933
- M2 → SSI_Clock Input (CLK) signal for the SSI protocol, input to the AEAT-9933
- M3 → SSI_Data Output (DO) signal for the SSI protocol, output from the AEAT-9933 SSI3 is available in two options per PSEL register setting:

Figure 15: SSI3-A Protocol Timing Diagram

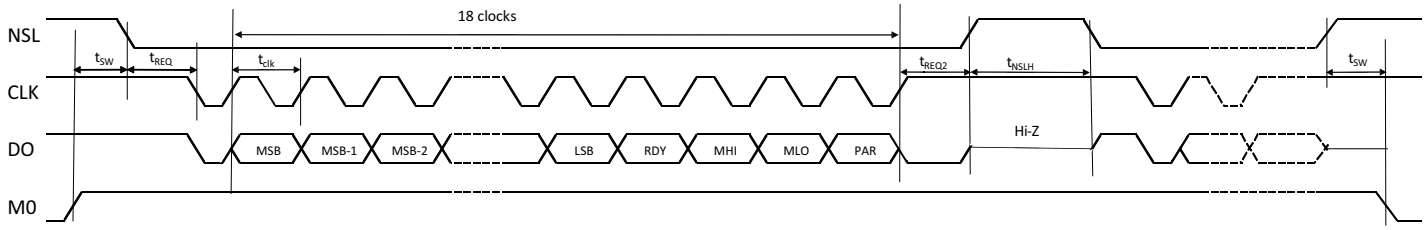


Default: SSI3A data output with 3-wire SSI up to 10-MHz clock rates. The DO pin is held at a high state once the NSL pin is high.

Table 11: SSI3 Protocol Timing

Symbol	Description	Min.	Typ.	Max.	Units
t_{sw}	Time between the M0 and NSL switching edges	1	—	—	µs
t_{clk}	Serial clock period	100	—	—	ns
t_{REQ}	CLK high time between the NSL falling edge and the first CLK falling edge	300	—	—	ns
t_{REQ2}	NSL low time after rising edge of last clock period for an SSI read	200	—	—	ns
t_{NSLH}	NSL high time between two successive SSI reads	200	—	—	ns

Figure 16: SSI-3(B)



SSI3-B with the DO pin is at tristate (high impedance) when the NSL pin is high.

Serial Synchronous Interface Two-Wire

The Serial Synchronous Interface Two-Wire (SSI2) protocol uses two pins from the AEAT-9933. These two pins are shared between UVW, SSI, and SPI protocols. MSEL (input pin) selects one protocol at a time. Assert 0 on the MSEL and M1 pins and 1 on the M0 pin upon power up.

- M2 → SSI_Clock Input (CLK) signal for the SSI protocol, input to the AEAT-9933
- M3 → SSI_Data Output (DO) signal for the SSI protocol, output from the AEAT-9933

Figure 17: SSI Two-Wire Timing Diagram

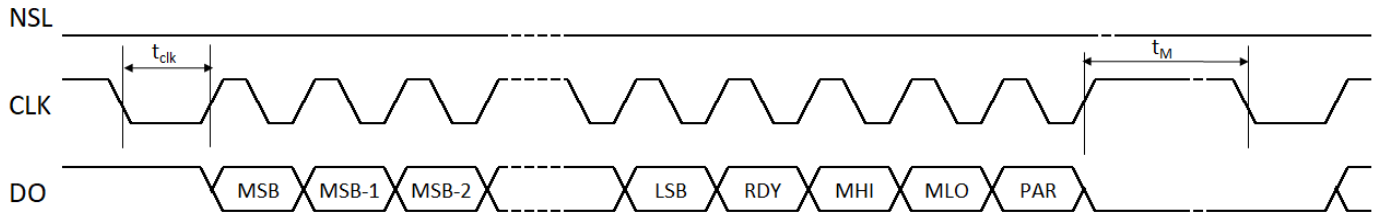
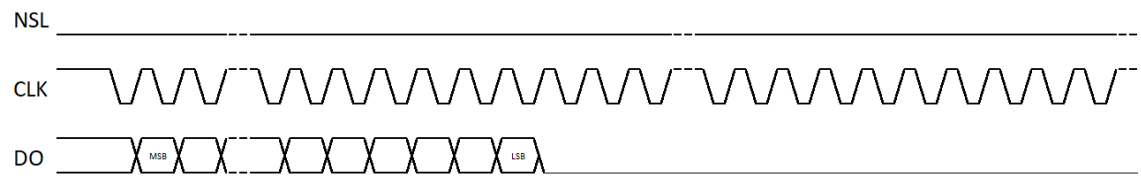


Table 12: SSI Two-Wire Timing Characteristics

Symbol	Description	Min.	Typ.	Max.	Units
t_{clk}	CLK low time after the first falling edge for an SSI read	250	—	t_M / 2	ns
t_M	CLK high time between two successive SSI reads	—	16.5	18.0	µs

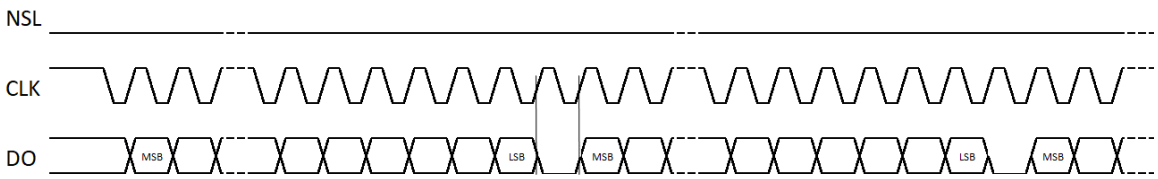
SSI2 is available in two options per the PSEL register setting.

Figure 18: SSI2 (A)



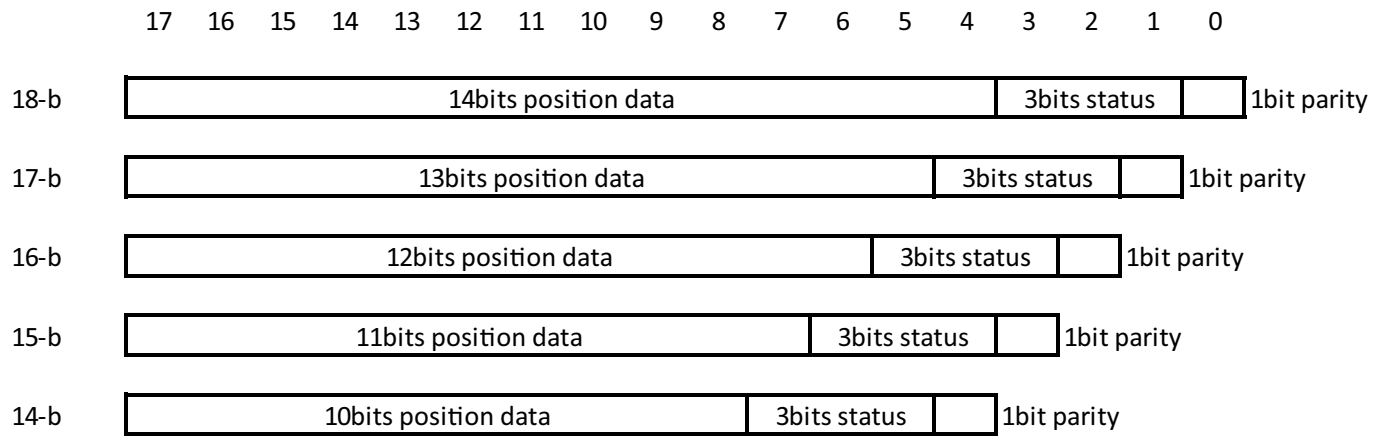
The output single data position remains low after LSB until the next monoflop (t_M) expires.

Figure 19: SSI2 (B)



The same position data can be continuously output by sending the clock train, and data is separated by a single low pulse. Data is refreshed until the next monoflop (t_M) expires.

Figure 20: SSI2 READ Data Format



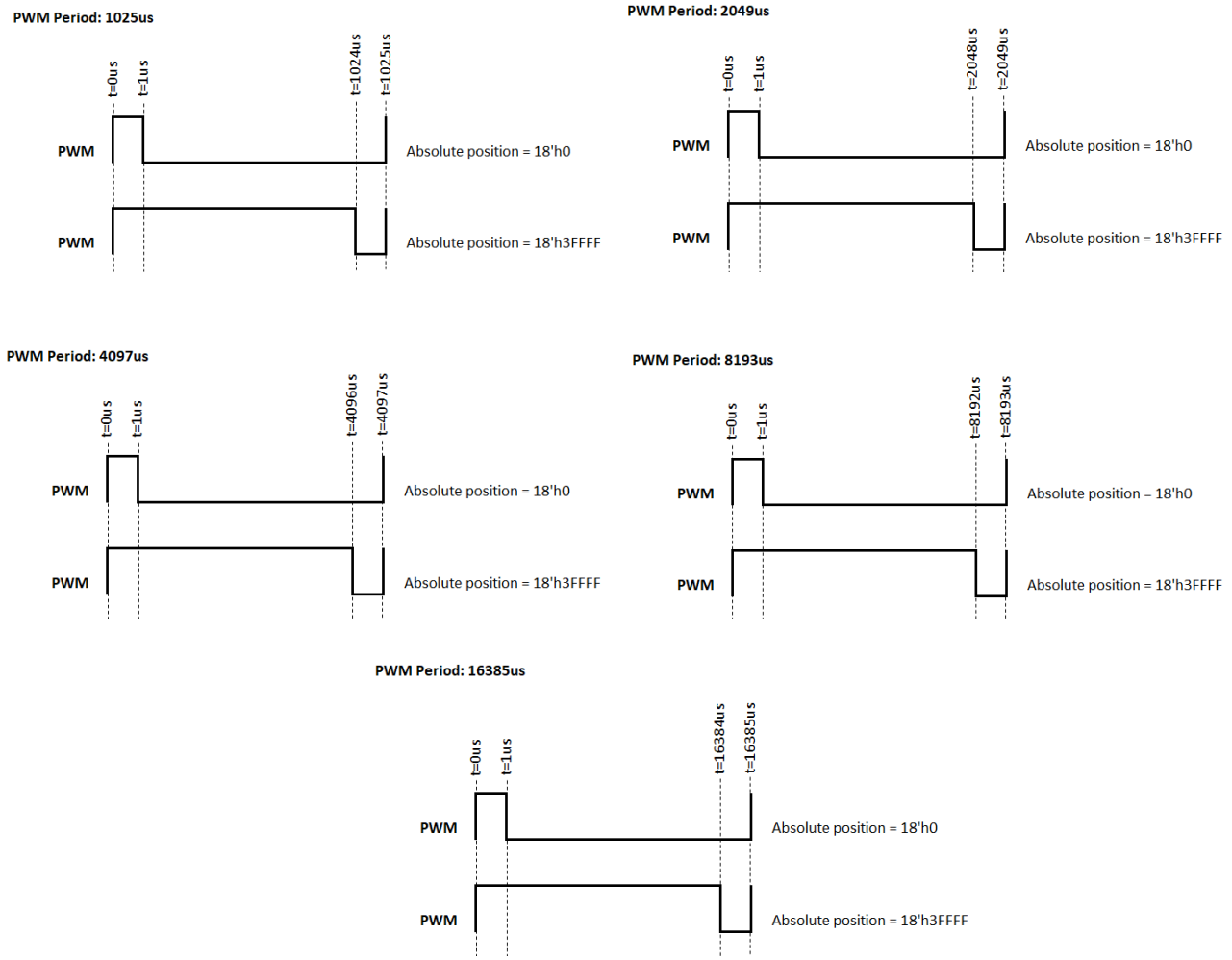
NOTE: 3-b status: {Ready, MHI, MLO}

- **Magnet High (MHI) Error** – This indicates that the magnet strength detected by the chip is too strong. When this is consistently flagged high, change the weaker magnet or increase the distance between the chip and the magnet. The value for this alarm is represented as 1.
- **Magnet Low (MLO) Error** – This indicates that the magnet strength detected by the chip is too weak. When this is consistently flagged high, change the stronger magnet or decrease the distance between the chip and the magnet. The value for this alarm is represented as 1.
- **Ready** – The chip is ready, and the ready value is 1.
- **Parity** – 1-b parity is even parity.

PWM

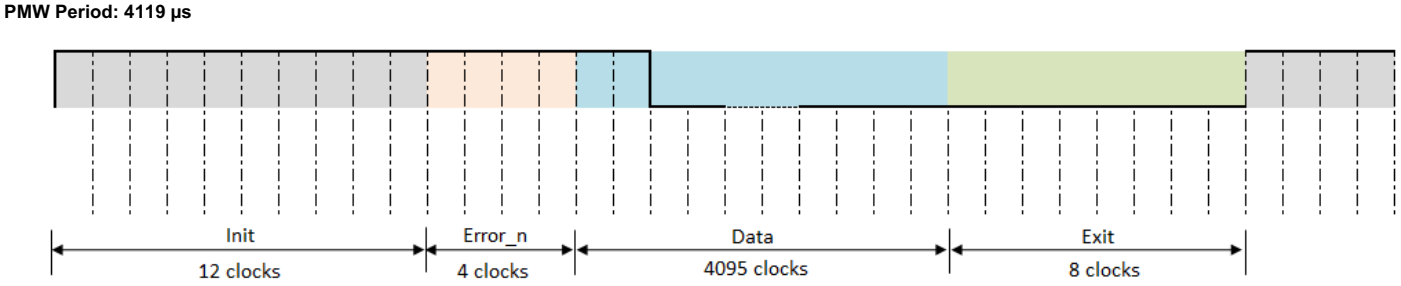
The PWM protocol uses one output pin (W_PWM) from the AEAT-9933. The W_PWM pin is shared between the UVW and PWM protocols. The PWM signals are configurable to have period of 1025, 2049, 4097, 8193, or 16385 µs. During power-up, the PWM signal is 0 before chip ready.

Figure 21: PWM Signals (Period = 1025/2049/4097/8193/16385 µs)



PWM protocols are also available with Init, Error_n, and Exit, along with Data information.

Figure 22: PWM Signals (Period = 1047/2071/4119/8215/16407 µs)



Incremental Output Format

The AEAT-9933 provides ABI and UVW signals to indicate the incremental position of the motor.

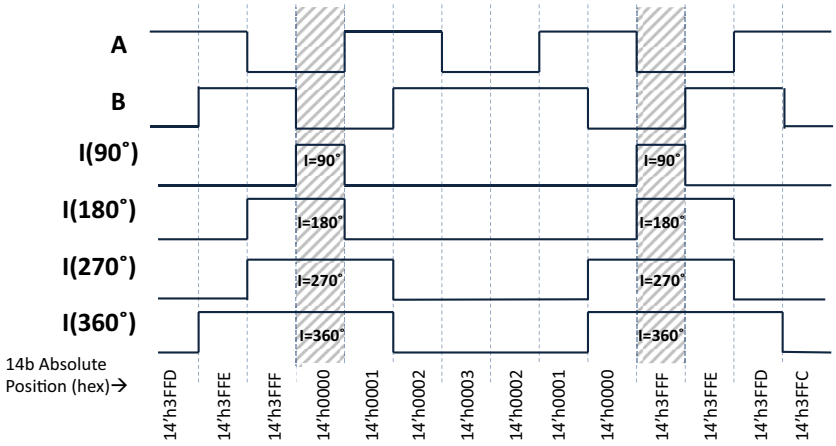
ABI

The ABI incremental interface provides position data and direction data from the three output pins (A, B, and I).

The index signal marks the absolute angular position and typically occurs once per revolution The ABI signal is configurable using the memory map registers. It supports the following configurations:

- Programmable CPR: 1 to 1024 CPR
- Programmable I-width: 90, 180, 270, or 360 electrical degrees (°e)
- Programmable I-State: 90, 180, 270, or 360 electrical degrees (°e)

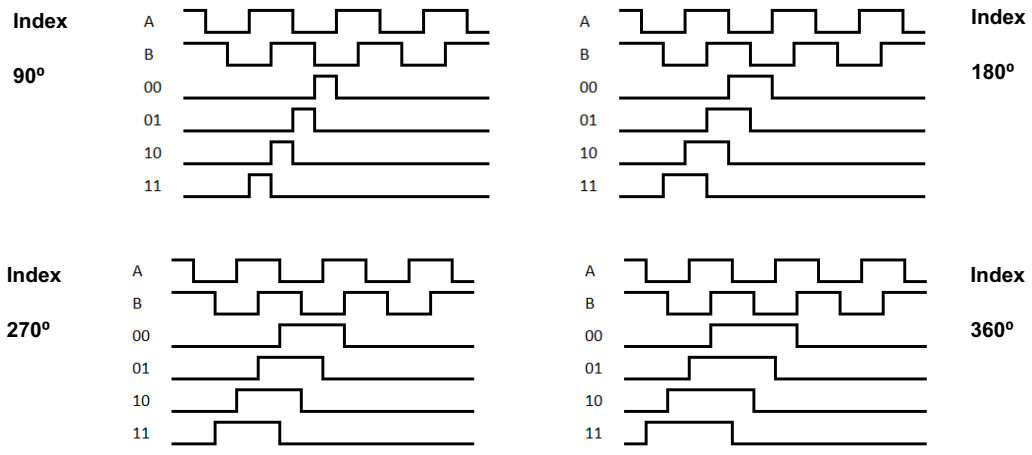
Figure 23: ABI Signal (1024 CPR with Different I-Width Settings)



NOTE: Assuming that the user sets hysteresis at the 0.02 mechanical degree:

- The Index position is configurable among the incremental state.
- The Index signal rises high once per revolution at the absolute zero position.

Figure 24: Index Signal Configuration

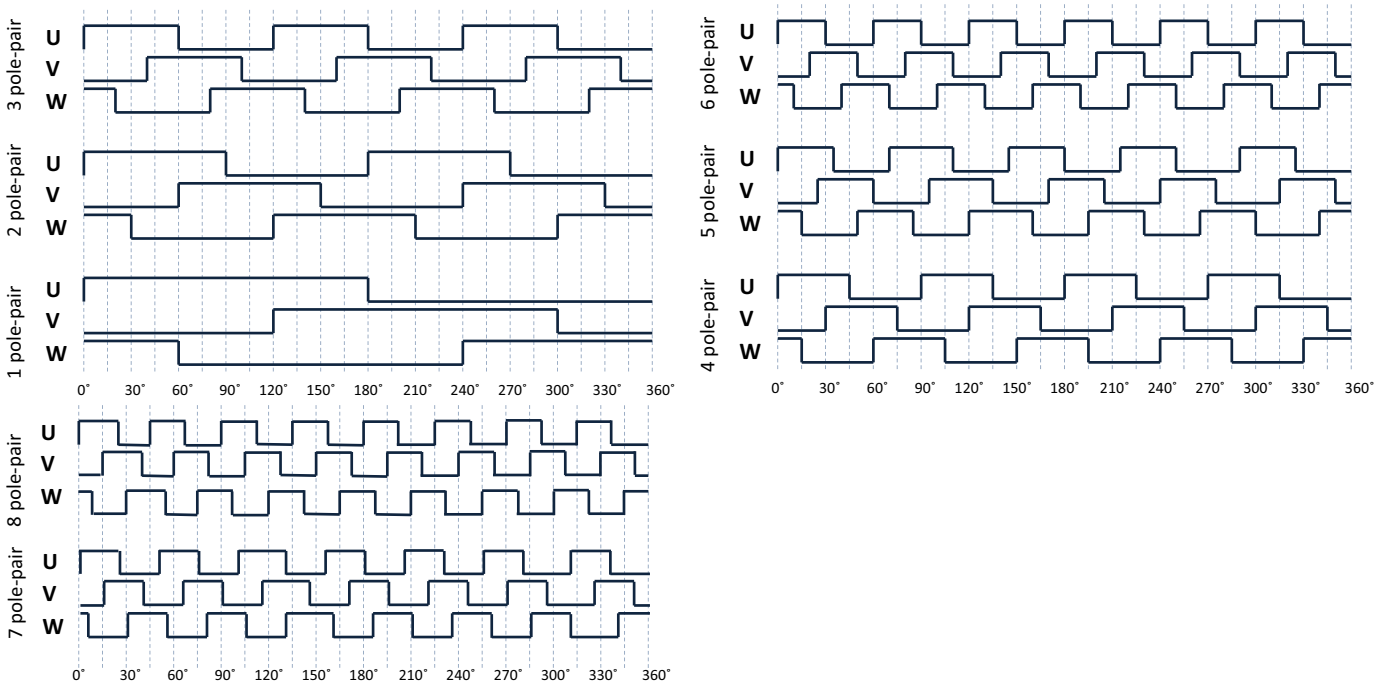


UVW

Three-channel integrated commutation output (U, V, W) emulates Hall sensor feedback and is available using three output pins. The AEAT-9933 can configure from 1 to 32 pole pairs, equivalent to 2 to 64 poles.

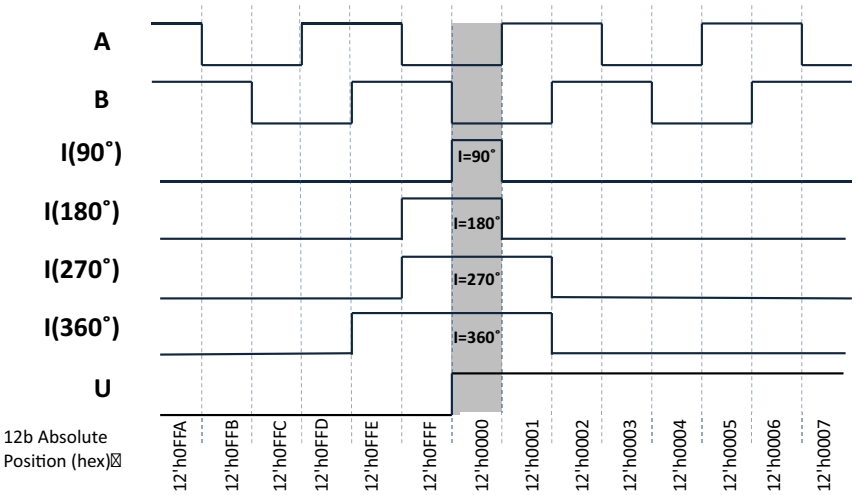
NOTE: The W_PWM pin is shared between the UVW and PWM protocols.

Figure 25: Commutation Output



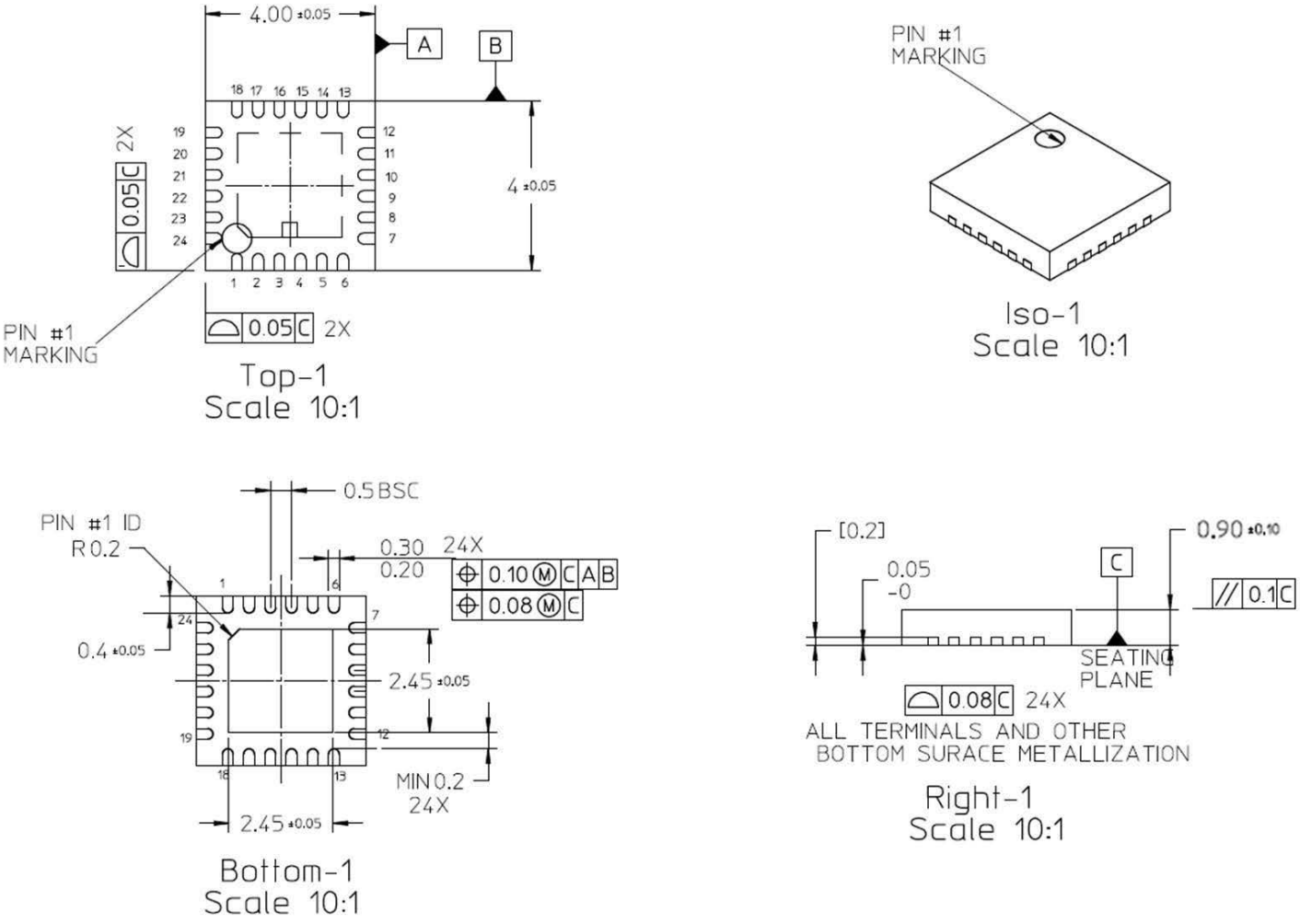
NOTE: Signal U from the UVW protocol is tagged to signal I from the ABI protocol, as shown in the following figure.

Figure 26: U-to-I Tagging



Package Drawings

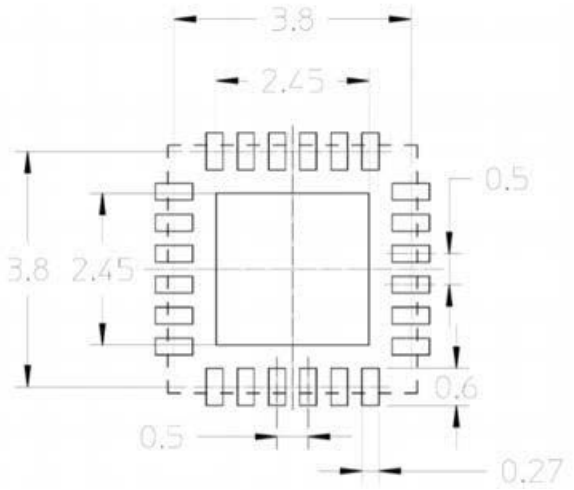
Figure 27: AEAT-9933, 24 QFN Dimensions



NOTE: Dimensions are in mm unless otherwise specified.

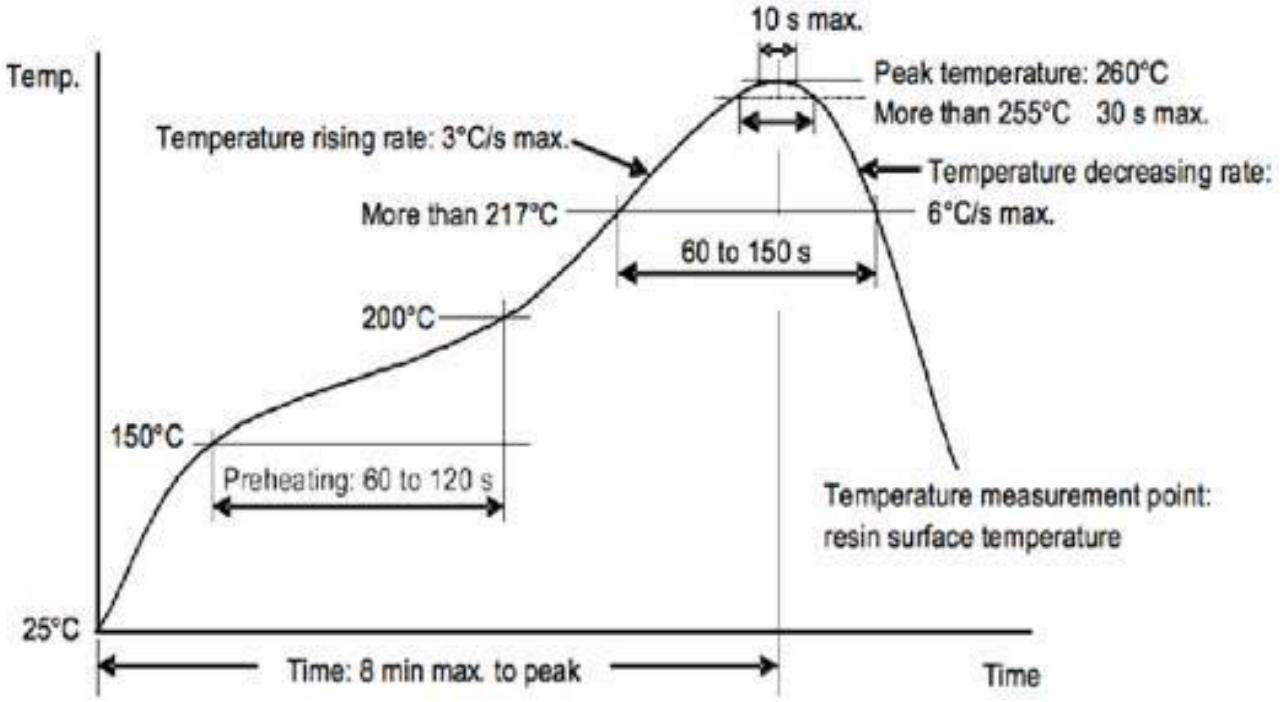
Recommended PCB Land Pattern and Soldering Profile

Figure 28: AEAT-9933, 24 QFN PCB Layout Land Pattern



NOTE: Dimensions are in mm unless otherwise specified.

Figure 29: Recommended Lead-Free Solder Reflow Soldering Temperature Profile



Product Ordering Information

Ordering Part Number	Product Description	Package	Delivery Form
AEAT-9933-100	14 Bits Magnetic Encoder On-Off Axis Tape and Reel 1000 pieces	QFN 24 leads, 4 mm × 4 mm	Tape and Reel
AEAT-9933-102	14 Bits Magnetic Encoder On-Off Axis Tape and Reel 100 pieces	QFN 24 leads, 4 mm × 4 mm	Tape and Reel
AEAT-9933-Q24	14 Bits Magnetic Encoder On-Off Axis Tube 73 pieces	QFN 24 leads, 4 mm × 4 mm	Tube

Packaging Information

Figure 30: Reel Dimensions

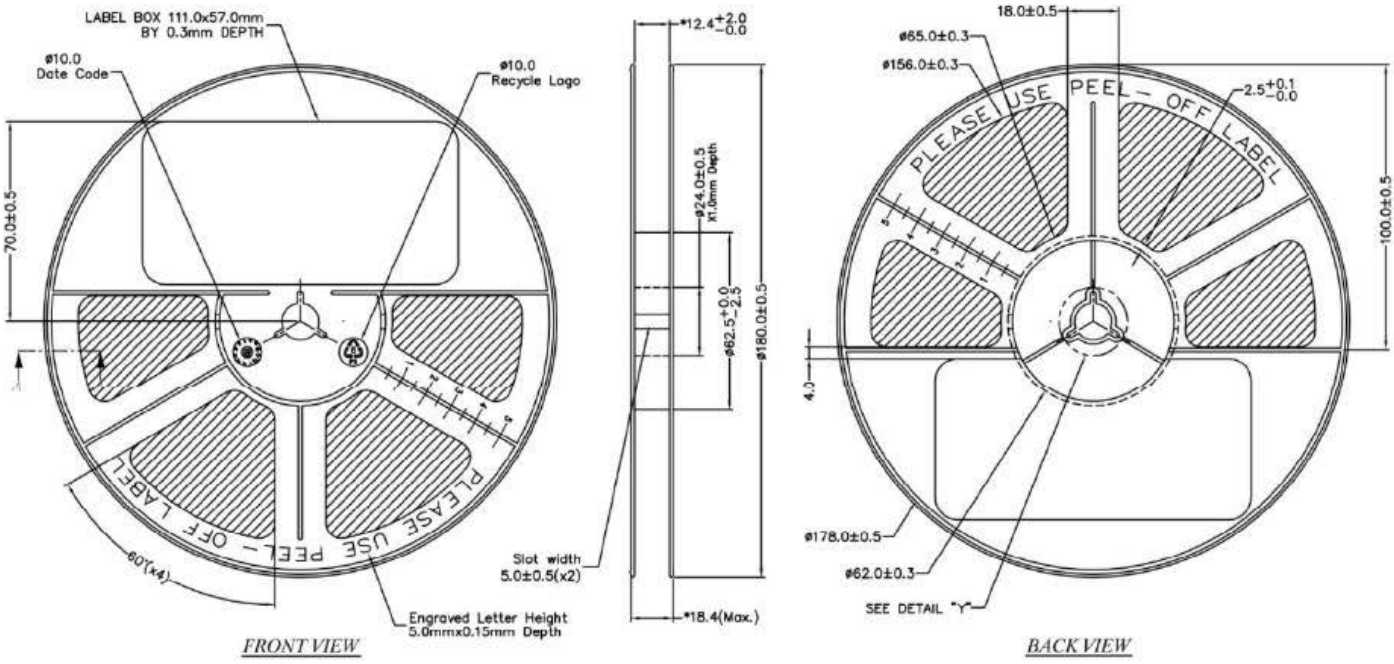


Figure 31: User Feed Direction

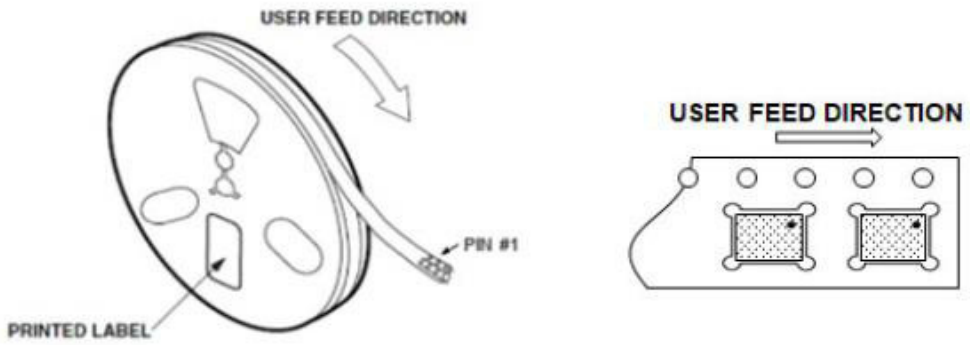
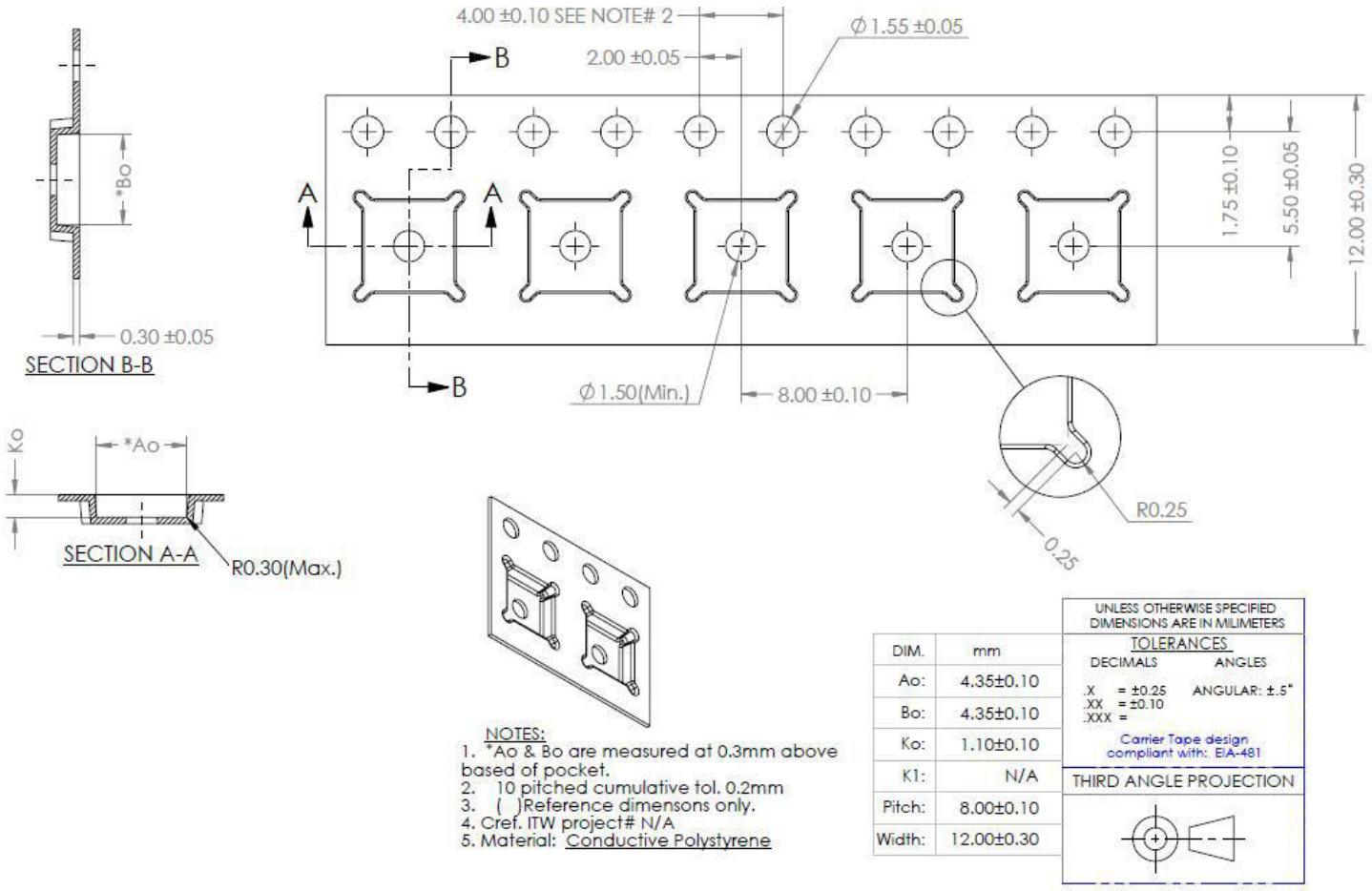


Figure 32: Top Cavity Dimensions



NOTES:
1. *Ao & Bo are measured at 0.3mm above based of pocket.
2. 10 pitched cumulative tol. 0.2mm
3. ( )Reference dimensons only.
4. Cref. ITW project# N/A
5. Material: Conductive Polystyrene

DIM.	mm
Ao:	4.35±0.10
Bo:	4.35±0.10
Ko:	1.10±0.10
K1:	N/A
Pitch:	8.00±0.10
Width:	12.00±0.30

UNLESS OTHERWISE SPECIFIED DIMENSIONS ARE IN MILIMETERS

TOLERANCES

DECIMALS: .X = ±0.25, .XX = ±0.10, .XXX =

ANGLES: ANGULAR: ±.5°

Carrier Tape design compliant with: EIA-481

THIRD ANGLE PROJECTION

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